How to use CyborgPi

1. Find IP address of pi
   1. Login with “pi”, “ramanlab”
2. Navigate to (cd) the CyborgPi folder
3. Navigate to the USEME directory
   1. Run LineFollow.py by running python LineFollow.py
      1. The program can be terminated with ctrl-c

On Shutdown

1. Shutdown the pi with the command “sudo shutdown now”
2. Wait around 30sec for the pi to fully shutdown
3. Flip the switch on the CyborgPi to fully power down the pi